

Autonomic Computing in a Beef-Production Process for Precision Livestock Farming

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Abstract

Precision livestock farming (PLF) offers farmers real-time monitoring and management system. PLF provides a real-time warning when something goes wrong so that the farmer can take immediate action to solve the problem. PLF introduces many new challenges and questions that must be resolved. Some of these challenges are related to the integration of grazing and animal health into the beef-production process. This article introduces an architecture for the self-managing of a beef-production farm. In particular, the architecture includes three autonomous cycles of data analysis tasks (ACODAT) that allow beef producers to have adequate coordination, optimization and planning of the productive process, which are: (i) circuit preparation, (ii) animal purchase, and (iii) animal fattening. This article also instantiates, in a farm, the autonomous animal-fattening cycle, as the first step towards efficient and effective beef-production processes. The main contributions of this architecture are (i) the ability to use everything mining to improve the knowledge of the system and decision-making processes, and (ii) three ACODAT for real-time analysis for sustainable and environmentally-friendly livestock production. The results are encouraging since the ACODAT allows smart management of the beef-production process, naturally introducing artificial-intelligence techniques to develop these tasks. Particularly, modeling using ACODAT allows an adequate description of a precision livestock process. Likewise, the preliminary results of some of the tasks of ACODAT are stimulating because they allow evaluating the feasibility of the proposal. For example, a first task for the identification of cattle fattening has a Mean Absolute Error (MAE) of 5.4 kg, which will be used by ACODAT to identify anomalies in the fattening pro-

29 *cess*. The instantiation of the animal-fattening cycle shows the viability and
30 robustness of this proposal.

31 **keywords:** Precision Livestock Farming, Autonomic Computing, Industry 4.0, Artificial
32 Intelligence, Beef Production, Data Analytics

33 1 Introduction

34 The *Food and Agriculture Organization* (FAO) states that sustainable development is the
35 management and conservation of natural resources, and the orientation of technological and
36 institutional change to ensure the continuous satisfaction of human needs for present and
37 future generations [1]. In parallel to the growing world-population, the demand for animal
38 protein is also increasing. Countries are reviewing the growth of animal production to meet
39 the growing demand for animal protein [2]. On the other hand, animal-care is critical to
40 design sustainable systems, given the loss of forest lands associated with a growing demand
41 for meat. Particularly, environmental-sustainability issues are acute. In the context of beef
42 cattle, (i) water use, (ii) land use, (iii) **biomass appropriation (for example, the animal**
43 **biomass as the feces and urine are natural fertilizers)** and (iv) greenhouse-gas emissions
44 are, for example, typically higher per unit of edible product, in beef systems, than in any
45 other livestock systems [3].

46 In particular, this work considers the relationship between pasture quality and animal
47 feed in the *Precision livestock farming* (PLF) framework [4]. Thus, this work focuses on
48 PLF but using existing technologies in precision agriculture farming (PAF) to improve
49 forage quality. In this way, it is necessary to consider specialized machinery for seeding
50 and fertilizing, the use of different sensors to obtain accurate information about the terrain
51 and weather, accurate soil analysis, among other aspects, to improve animal production,
52 harvest forage more efficiently, and reduce environmental impact [5].

53 Specifically, knowing the conditions of the farm helps to define an adequate feeding
54 for the animal [6]. A good combination of forage and soil guarantees optimal results in
55 cattle and dairy farms. The relationship between the soils of cattle farms, the types of
56 fodder that are planted on them, and the cattle on the ranch, has recently been used to
57 define strategies to improve the productivity and sustainability of the cattle sector [7]. In
58 this sense, decisions are necessary on the quality of the seed, the fertilization plan, the
59 irrigation system, phytosanitary management, weed control, and grazing programming,
60 among other aspects, as important factors to increase yield forage and nutritional value to
61 improve livestock productivity.

62 An initiative that aims to improve sustainability is PLF through the monitoring of
63 animals in a herd. Examples of PLF are the following works. Qiao *et al.* [8] identified
64 livestock by video, using artificial intelligence techniques such as Neural Networks. In ad-
65 dition, Denis *et al.* [9] used regularized change-point-estimation and the k-means algorithm
66 for a better understanding of the lactation process. Likewise, Achour *et al.* [10] applied
67 unsupervised automated-monitoring of dairy cows' conduct based on an inertial magnitude
68 unit attached to their reverses. Finally, Guo *et al.* [11] identified the animal poses based on
69 bilateral symmetry applied to the measurement of cattle body in point clouds. All these
70 works have been focused on improving production by means of PLF. In this sense, PLF
71 is a new approach –based on the use and development of information and communication
72 technologies– to achieve automatic, accurate, real-time monitoring and analysis of animal
73 behavior, which helps the producer to make decisions [12].

74 Previous works on PLF have not taken into account *soil variables*, which, together
75 with *animal activity*, could lead to create robust models to improve grazing methods, and,
76 as a consequence, to a higher production [12]. The objective of this work is to combine

77 grazing with animal health using the paradigm of *autonomous cycles* [13]. This paradigm
78 defines a set of data-analysis tasks for the self-management of a system. *Autonomous cycles*
79 *of data analysis tasks* (ACODAT) provide cattle ranchers with tools for decision-making.
80 Examples of the benefits of the use of ACODAT, in PLF, could be: (i) to maintain a
81 high production of good-quality forage for the longest period of time, (ii) to maintain a
82 favorable balance among forage species, (iii) to obtain efficient use of the forage produced,
83 (iv) to achieve a profitable livestock production, and (v) to prevent diseases.

84 Each of the above benefits could use the specification of an ACODAT. In addition, to
85 achieve these benefits, the beef-production farms must have the technology to capture and
86 process the necessary data to build the knowledge models defined in an ACODAT. The
87 main contributions of this research are the following.

- 88 • The use of the autonomous-computing paradigm to define an architecture for the
89 self-managing of beef-production farms.
- 90 • The ability to integrate various mining techniques (e.g., data mining and process
91 mining) to generate knowledge models of the farm.
- 92 • The definition of several ACODAT –with different goals about the beef-production
93 process– to allow real-time analysis and to help decision-making for sustainable and
94 environmentally-friendly livestock production.
- 95 • The integration of multiple variables about soil, animal welfare, pasture, and climate
96 for the analyses.

97 This is a theoretical proposal that aims to show the feasibility of using the ACODAT
98 concept to model PLF. The preliminary results of some of the analysis tasks that compose
99 the ACODATs are encouraging. For example: the ACODAT that supervises the animal
100 fattening process is composed of a task that defines a cattle weight identification model
101 using machine learning techniques for the detection of anomalies [14], and a system to
102 diagnose the anomaly in the cattle fattening process in rotational grazing using a fuzzy
103 classification system [15]

104 This article is organized as follows. Section 2 presents related work. Section 3 in-
105 troduces ACODAT and shows the methodology used in this work. Section 4 shows the
106 proposed architecture for beef production in the context of PLF and, briefly, describes the
107 three *autonomic cycles* (AC) for the self-management of a beef-production process. After,
108 Section 5 describes the specification of an AC for self-planning of paddock rotation and its
109 instantiation in a case study. Finally, Section 6 shows a comparison with previous work,
110 and the article ends with conclusions in Section 7.

111 2 Related Works

112 With PLF and data-mining tasks, considerable progress has been made in the use of tools to
113 –routinely– cover and collect information from animals and farmsteads in a lower laborious
114 manner than before, generating large volumes of data [16]. In what follows, this section
115 presents related works on PLF and grazing with animal health.

116 For the problem of grazing automation and animal health, Segerkvist *et al.* [17] pro-
117 posed a method, based on an unmanned automatic precision-weighing system –that can
118 be used in pastures–, which alert farmers when animals show abnormal weight-gain curves.
119 This work is –primarily– focused on detecting pasture-borne nematode-parasite infections
120 that reduce calf weight-gain.

121 For the problem of weighing, Feng *et al.* [18] proposed a dynamic-weighing algorithm,
122 for cows, based on support vector machines and empirical wavelet transforms for classifi-
123 cation. The dynamic-weight curve is obtained using a weighing device placed along a cow
124 travel corridor, and data is preprocessed using signal acquisition, feature extraction and
125 normalization techniques. The results are divided into three levels during the movement:
126 low, medium and high. Finally, recently, a model of normal weight identification in cattle
127 was designed [14].

128 In addition to automatic weighing, monitoring is also important –as many operations
129 are performed manually in livestock farms. Jung *et al.* [19] proposed a livestock-tracking
130 system based on *Wireless Sensor Networks*. The livestock-tracking system can monitor
131 farm animals using the *Internet of Things* (IoT) and cloud platforms. Through a collar on
132 the neck of an animal, using IoT equipment, the system monitors the activity of the live-
133 stock. Fuentes *et al.* [20] proposed an artificial-intelligence system to increase milk quality
134 by reducing heat stress. Particularly, rising global temperatures and climatic anomalies,
135 such as heat waves, are affecting heat-stress levels of farm animals. These impacts have
136 detrimental effects on the milk quality and productivity of dairy cows. Fuentes *et al.* ar-
137 gued that their system allows to –automatically– assess animal welfare, productivity and
138 milk quality.

139 A task in monitoring is tracking. To solve this problem, Vayssade *et al.* [21] proposed
140 a method to process images, taken by a commercial drone, to automate the tracking of
141 animal activities. Their method, automatically, detects goats from images and tracks their
142 activity using a combination of thresholding and supervised-classification methods. In
143 another work, using drones, Li *et al.* [22] deployed a cluster of Unmanned Aerial Vehicles
144 (UAV) to -autonomously- track and monitor livestock –such as cattle and sheep– in a
145 pasture. Li *et al.*'s goal was to find the optimal deployment of UAV to minimize the
146 average UAV-Animal distance, using a standard k-means clustering algorithm.

147 In another work using images, Benze *et al.* [23] designed and implemented a computer-
148 vision system for cow individual food-intake measurement, based on deep Convolutional
149 Neural Networks, and a low-cost RGB-D (Red, Green, Blue, Depth) camera. Timmerman
150 *et al.* [24] designed a multi-layer monitoring support system to help the poultry farmer.
151 The multi-layer support system consists of a static system for flock observation (an existing
152 PLF technology), and robot(s) to observe bird health and behavior, in order to perform
153 daily routine tasks.

154 Finally, Germani *et al.* [25] designed and implemented an IoT architecture to contin-
155 uously monitor livestock, in barns, during grazing. Germani *et al.* adopted the *LOn*
156 *RA*ng (LoRa) *low-power wide-area network* (LPWAN) technology to cover diverse envi-
157 ronments, and a suitable configuration of web services to perform data storage, analysis
158 and visualization.

159 All the previous works above focused on monitoring or capturing animal behavior;
160 however, in the case of grazing, they did not use soil data. Similarly, they did not combine
161 animal welfare with pasture intake. These limitations were also highlighted in a recent
162 systematic literature review [12]. To overcome such limitations found in previous works,
163 this article focuses on the use of soil variables for optimal decision-making on grazing and
164 autonomous beef production.

165 3 Autonomous Cycles of Data Analysis Tasks

166 This section presents a background on data-mining tasks in PLF and ACODAT.

167 3.1 Definition of ACODAT

168 Autonomous computing is a paradigm in which the computing system as a whole offers
169 much more capabilities than the sum of its parts, with self-management capabilities to
170 adapt to its environment [26]. *Autonomic cycles of data analysis tasks* (ACODAT) have
171 been defined by Aguilar et al. [27], [28], [29] as a set of data analysis tasks that act
172 autonomously to supervise and/or control a process. These Data Analysis tasks are based
173 on knowledge models (e.g., prediction, description, diagnosis, among others), and they
174 interact and interrelate with each other according to the objectives of the cycle. Each
175 data analysis task has a different function: (i) to observe the process, (ii) to analyze and
176 interpret what is happening in the process, and (iii) to make decisions to improve the
177 process.

178 ACODAT has been used in different domains; for instance, in smart classrooms [27], [29]
179 and Industry 4.0 [30], [31], [32]. These works based on ACODAT present a different way
180 of introducing the autonomous computing paradigm in smart classrooms and in industry
181 4.0 to previous works [33], [34], [35], since ACODAT is based on data analysis tasks that
182 can be self-managed.

183 ACODATs are designed using the *Methodology for the development of data-mining*
184 *applications based on organizational analysis* (MIDANO) [36]. MIDANO integrates data
185 analysis tasks into a closed-loop that can solve complex problems. In this sense, it is
186 essential to integrate data-analysis tasks in a consistent way to generate strategic knowledge
187 useful to achieve business objectives. A detailed description of the function, of each task
188 category, in ACODAT, is explained in what follows.

- 189 • **Monitoring:** Tasks responsible to observe the monitored system. These tasks
190 must capture data and information about the behavior of the system. In addition,
191 these tasks are responsible for data preparation (e.g., preprocessing and selection of
192 relevant features) for the following steps.
- 193 • **Analysis:** These tasks interpret, understand and diagnose what is happening in the
194 monitored system. Particularly, these tasks allow building *knowledge models* from
195 the dynamics observed in the system, oriented to know what is happening in the
196 system.
- 197 • **Decision-making:** These tasks define and implement the necessary actions, based
198 on previous analysis, to improve or correct the failures of the monitored system.
199 Thus, these tasks affect the dynamics of the monitored system. The effects of the
200 decision-making tasks are evaluated by the monitoring and analysis tasks, restarting
201 a new iteration of the cycle.

202 The development of these specialized tasks (Monitoring, Analysis, and Decision-Making)
203 depends on the context. For example, if one wishes to develop data-based models for di-
204 agnosing or predicting behavior, one can use the “Cross-Industry Standard Process for
205 Data Mining” (CRISP-DM) methodology. On the other hand, if one wishes to develop a
206 decision-making model using expert knowledge, one can use the “Knowledge Discovery in
207 Databases” (KDD) methodology. In section 6.2, we present a discussion about it.

208 In this work, we will propose a PLF approach based on ACODAT. It is the first
209 time that ACODAT has been applied to PLF, in a deployment environment as broad and
210 complex as farms with cattle rotation. In addition, it is the first time that ACODAT has
211 been proposed in a context with a great diversity of data sources (see section 4.2), which
212 has a large number of sensors to be considered.

213 3.2 Methodology to develop ACODAT

214 The methodology used in this work is MIDANO [36]. MIDANO is used to develop data-
215 mining applications based on organizational analysis. MIDANO is designed to develop
216 applications based on ACODAT. MIDANO consists of three phases.

217 **Phase 1.** Identification of the sources of knowledge in an organization: The main
218 objective of this phase is to know the organization, its processes and its experts, in order
219 to define the objective of the application of data-analysis techniques in the organization.
220 In addition, in this phase, a specification of the ACODAT to be developed is made.

221 **Phase 2.** Data preparation and processing: This process is based on the extraction
222 of data from its sources, transformation of the data, and the load of the data into the AC
223 data warehouse. To carry out this process, a feature engineering process is carried out
224 in order to select the main variables of the studied process. Finally, a mineable view is
225 created, which is composed of the description of all the variables of interest.

226 **Phase 3.** Development of the ACODAT: This phase aims to implement the different
227 data analysis tasks of the ACODAT, which generate the required knowledge models (e.g.,
228 predictive models and descriptive models). This phase ends with the implementation of
229 a prototype of each AC. During this phase, experiments are performed to validate the
230 knowledge models generated by the data-analysis tasks.

231 In this research, MIDANO has been used for the definition of ACODAT to improve the
232 production process of a beef farm. The data sources analyzed were animal-weighing history,
233 animal welfare, soil quality of each paddock, climate, temperature, pastures, paddock
234 rotations, and sale and purchase price of animals. Table 1 summarizes the use of MIDANO
235 in this work.

Table 1: Use of MIDANO Phases in this work

Phases	Use
Phase 1	Analysis of grazing and animal-health management process. For that, this research proposes several ACODATs to improve the beef-production process.
Phase 2	Identification of data sources (e.g., pasture, soil, animal weight) and definition of the multi-dimensional data model
Phase 3	Implementation of the ACODAT for the beef-production process. This paper presents the instantiation of one of them.

236 4 Proposed Architecture

237 This section presents the proposed architecture for beef production based on PLF. This is
238 one of the main contributions of this work.

239 4.1 General Architecture

240 In this research, we propose an architecture for beef production in PLF (see Figure 1),
241 based on the Autonomic-Computing Paradigm [26], [37]. This paradigm is an essential
242 element that guarantees the autonomy and adaptability of the production process. Au-
243 tonomic properties, like (i) self-configuration, (ii) self-planning, and (iii) self-optimizing,
244 are developed to endow autonomy in the production process. This architecture has four
245 layers: (i) monitoring, (ii) network, (iii) data processing and (iv) business; these layers are
246 described below.

- 247 1. **Monitoring:** This layer captures soil, water, animal behavior and climate variables
 248 through IoT-based sensors. After, data is stored in a cloud server. This layer can
 249 be extended by allowing the effective integration of new types of sensors [38]. **Some**
 250 **examples of variables captured directly by the sensors, or derived from the sensed**
 251 **data, are the amount of forage per paddock, amount of quality forage per paddock,**
 252 **amount of water in the drinkers, amount of rain per day, movement of animals,**
 253 **pasture yield, among others.**
- 254 2. **Network:** This layer is in charge of communication between the sensors and the
 255 server in the cloud.
- 256 3. **Data management:** This layer stores, verifies, pre-processes, and protects data.
 257 These data will be made available to the beef farmer.
- 258 4. **Business:** This layer is in charge to improve the beef-production process using
 259 ACODAT for decision-making. Particularly, data analysis tasks based on everything-
 260 mining techniques generate knowledge for the automation of the beef-production
 261 process (see the Reflexive Layers in Fig. 1) [30]. Thus, the analytical tasks gener-
 262 ate useful information. Some examples of decisions or information that will be
 263 obtained in this layer are: the optimal stocking capacity per paddock supported by
 264 the livestock farm, detection of animal diseases, forage status per paddock, animal
 265 welfare, and weed detection. In addition, the architecture has an alert system –in
 266 the reflexive layer– used autonomously by the tasks that require alerts.

267 **The next sections explain in detail the ACODATs we are proposing for holistic man-**
 268 **agement of the entire beef production process, and a case study to explain in detail the**
 269 **implementation of the data analysis tasks for one of them.**

270 4.2 ACODAT in beef production

271 This section deals with AC design for the beef-production process. We propose a system
 272 of ACs (named ACPLF-000, see Fig 2) composed of three ACODAT: (i) preparation of
 273 the circuits, (ii) animal fattening, and (iii) animal purchases. ACPLF-000 allows the (i)
 274 self-management, (ii) self-planning, and (iii) self-supervision of the production process.

275 The goal of ACPLF-000 is the self-planning of the rotational grazing in the process of
 276 beef production. Specifically, the objective of each AC of ACPLF-000 is the following.

277 **ACPLF-001 (Circuit preparation):** This is in charge to prepare paddocks. As
 278 an example, to verify the state of: (i) drinking troughs, (ii) electric fences, (iii) pasture
 279 capacity, and (iv) animal-carrying capacity per circuit.

280 **ACPLF-002 (Animal purchase):** This is in charge (i) to select the best supplier
 281 (i.e., another livestock farm or livestock auction), and (ii) to select the animal lot with the
 282 best characteristics.

283 **ACPLF-003 (Animal fattening):** This is in charge to manage the animal’s fatten-
 284 ing process. This cycle carries out the tasks of (i) animal weighing, (ii) animal vaccination,
 285 (iii) definition of the forage capacity per paddock, (iv) equipment verification, and (v) ro-
 286 tation; depending on the planning process. As an example, if an animal reaches a weight
 287 greater than 450kg, then this animal is moved to lots –with special pastures– for its fat-
 288 tening completion.

289 These three ACs can be executed –in parallel– when there is a production in process,
 290 and –in series– when a new production is started. As an example, when a new production
 291 is started, it is necessary (i) to prepare the land, (ii) to wait for the grass to grow, (iii)
 292 to measure the forage to calculate the stocking rate, (iv) to purchase the animals, and,
 293 finally, (v) to monitor their fattening.

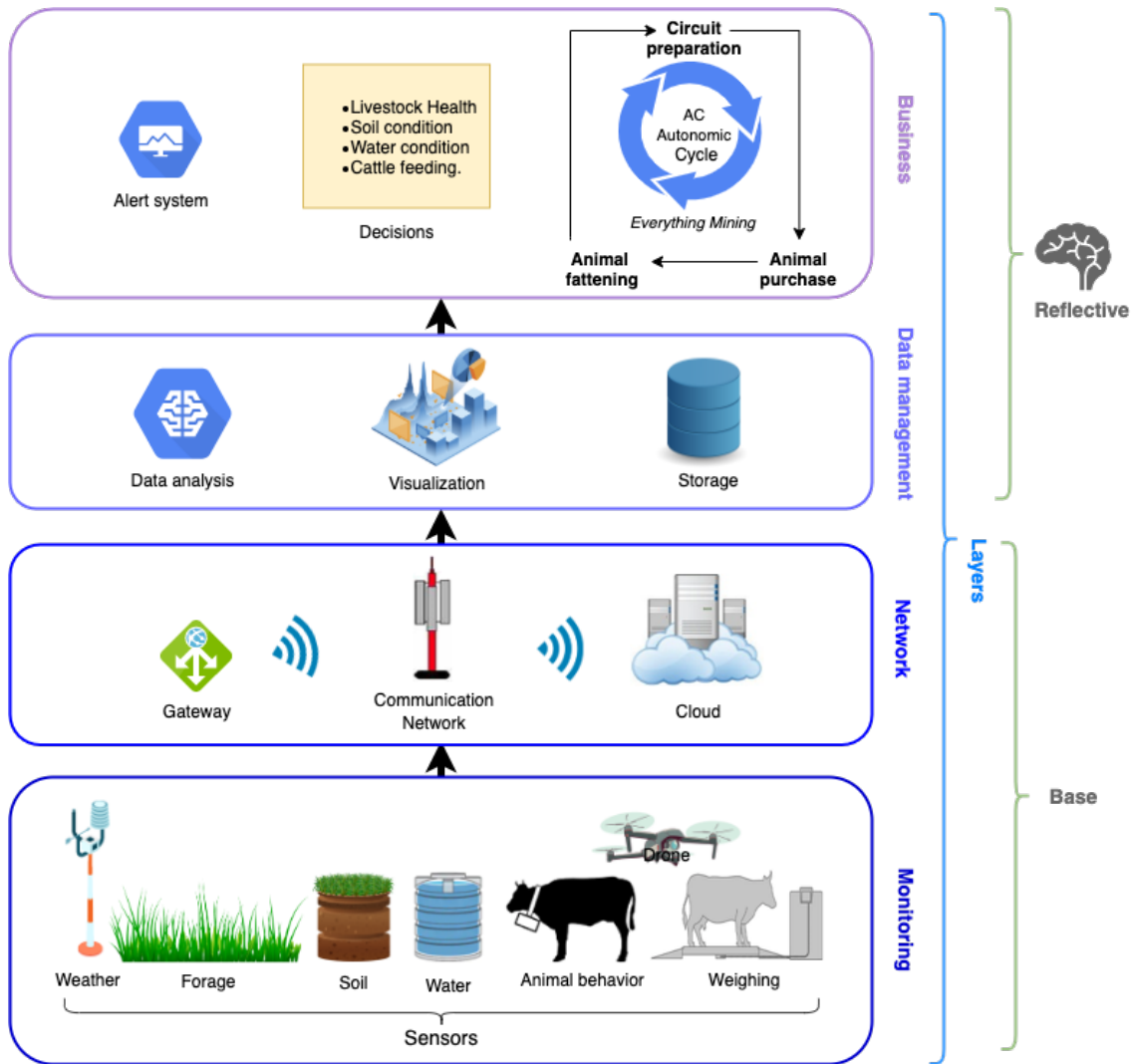


Figure 1: Autonomic architecture for a beef-production process based on PLF

294 4.2.1 ACPLF-001 Specification: Circuit preparation

295 The aim of this AC is to verify and configure the process of beef production based on the
 296 objective of efficient production. Mainly, this cycle is composed of three tasks (see Fig. 3).

297 The first task, named the Forage task, is in charge to recommend grass seeds based on
 298 the soil characteristics of each paddock. The second task has two subtasks, the first subtask
 299 is in charge to detect weeds to determine in which paddock and with what intensity the
 300 weeds are found, and the second subtask must calculate the forage capacity per paddock.
 301 Finally, the last task estimates the animal carrying per paddock. Table 2 shows the general
 302 description of each task of this AC.

Table 2: Description of the Tasks of ACPLF-001. Abbreviations: DB = Data Base.

Task Name	Knowledge models	Data Sources
1. Determine the best seed for a specific paddock.	Recommendation Model	Farm DB (Sensor data), Seed-sale website
2. Determine the amount of weeds	Detection Model	Farm DB (Drone Data)
3. Determine the fodder for each paddock.	Detection Model	Farm DB (Drone Data)

Table 2 continued from the previous page

4. Determine how many animals can be in the pasture depending on the forage (Carrying capacity for paddock).	Estimation Model	Farm DB (Sensor data, Drone Data)
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303 **Task 1. Determine the best seed for a specific paddock:** This task is a grass-
304 seed recommendation model that uses the soil sensors of the paddocks. This task captures
305 the physicochemical variables of the soil, and, after, it determines which is the best seed
306 to sow depending on the need and type of paddock. Examples of the types of paddocks
307 are (i) quarantine, (ii) fattening and (iii) finishing. In addition, in this task, the attributes
308 and prices of each seed are reviewed on specialized seed websites.

309
310 **Task 2. Determine the amount of weeds in each paddock:** This task detects
311 the amount of weeds in the paddock (e.g., using images of the paddocks).

312
313 **Task 3. Determine the fodder of each paddock:** This task determines the weight
314 of grass (biomass) per paddock (e.g., using images of the paddocks). Biomass is a funda-
315 mental input to calculate animal-carrying capacity.

316
317 **Task 4. Determine Carrying capacity per paddock:** This task determines how
318 many animals can be, in the pasture, depending on the forage. This task invokes an opti-
319 mization system that defines how many animals each paddock can support. This system
320 uses variables such as climate, forage capacity, pasture type, pasture quality and animal
321 welfare (e.g., percentage of shadow, water availability and feed supplements per paddock).

322
323 ACPLF-001 configures the initial conditions for the process of animal fattening on the
324 farm. ACPLF-001 computes initial parameters, such as the number of animals per paddock
325 and pasture inventory.

326 4.2.2 ACPLF-002 Specification: Animal purchase

327 The objective of this AC is the selection of suppliers and lots of cattle for purchase. This
328 cycle is composed of two tasks (see Fig. 4). Table 3 shows the data sources used, in this
329 AC, for each task.

Table 3: Description of the Tasks of ACPLF-002. Abbrevia-
tions: DB = Data Base.

Task Name	Mining Techniques	Data Sources
1. Determine the best supplier	Classification model	Social network, Cattle-auction website, Farm DB
2. Determine the best herd of animals	Classification model	Social network, Cattle-auction website, Cameras

330 **Task 1. Determine the best supplier:** This task ranks the best cattle supplier
331 using different criteria such as (i) location, (ii) price, (iii) healthy-animal history and (iv)
332 delivery time.

333
334 **Task 2. Determine the best herd of animals:** This task uses a model that esti-
335 mates the quality of livestock using different data sources. As an example, this task can
336 estimate (i) breed-purity percentage, (ii) best animals and (iii) health condition.

337
338 ACPLF-002 is in charge (i) to select the best animal suppliers (using the score of a

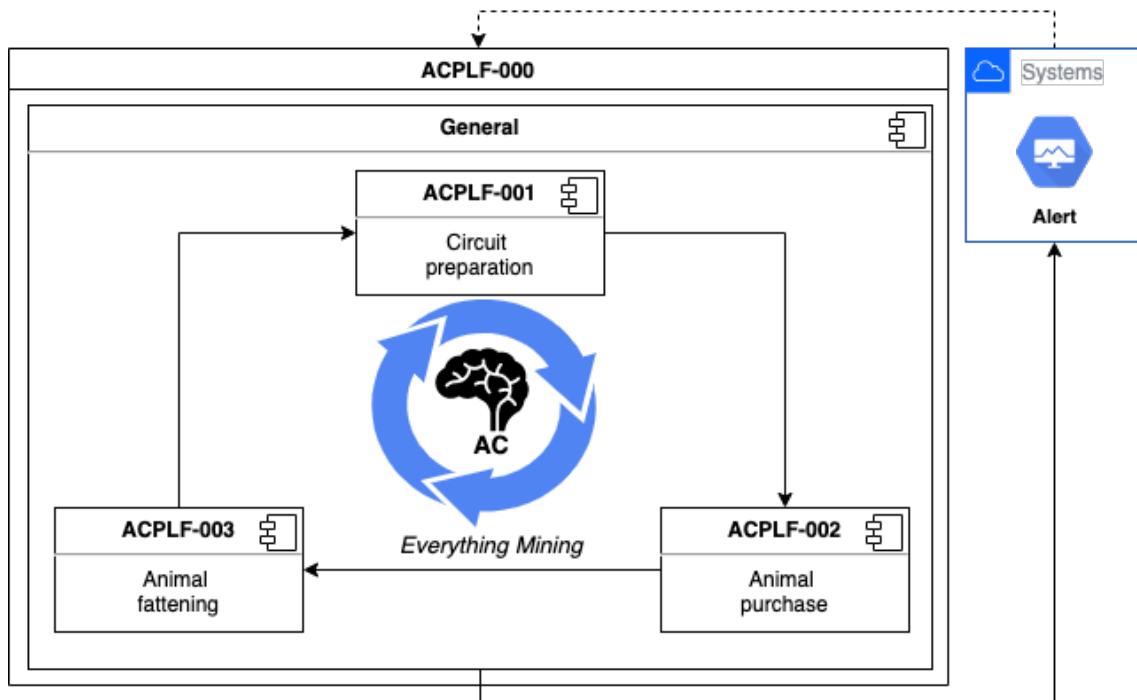


Figure 2: ACPLF-000: AC design for the beef-production process.

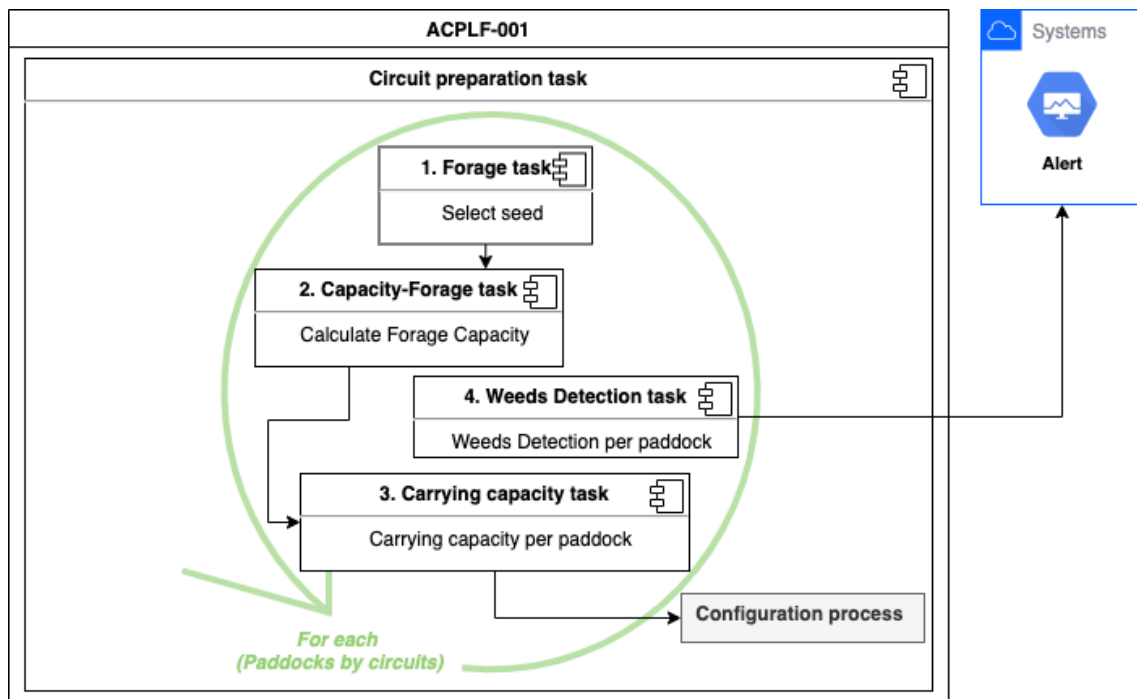


Figure 3: ACPLF-001: Circuit preparation

339 supplier in the system), and (ii) to select the best herd of animals for purchase (considering
 340 season and market prices).

Table 4: Description of the Tasks of ACPLF-003. Abbreviations: DB = Data Base.

Task Name	Mining Techniques	Data Sources
1. Weighing task	Estimation model	Farm DB
2. Vaccination task	Prescriptive models	Farm DB
3. Rotation task.	Assignment Model	Farm DB

347 **Task 1. Weighing task:** This task uses the history of the previous weighing and
 348 estimates cattle weight and health status.

349
 350 **Task 2. Vaccination task:** This task is based on a prescriptive model to determine
 351 the actions to follow in the vaccination plan (including deworming and vitamins). The
 352 main objective of this task is to reduce costs and improve profits.

353
 354 **Task 3. Rotation task:** This task uses data from sensors located throughout the
 355 farm, and other data sources (e.g., images of the farm, climate, pasture type and animal-
 356 welfare variables), to assign the best paddock available for weight gain.

358 4.2.4 Data model

359 The multidimensional data model, for the previous ACs, is defined in this section.

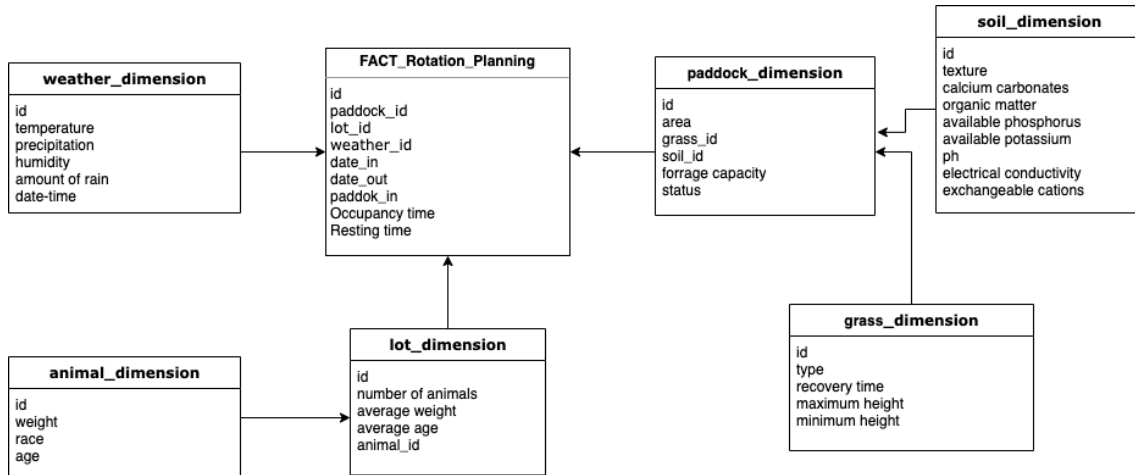


Figure 6: Multidimensional Model

360 Figure 6 describes the multidimensional data model required by the ACODAT for
 361 smart farm management. Each dimension represents and characterizes each information
 362 source (animal, paddock, etc.) necessary during the management process. The data model
 363 in Figure 6 includes data from different sources, specifically, from farm databases (e.g.,
 364 livestock-inventory systems), climate data obtained from the Internet, and sensor data
 365 captured in the monitoring layer that are in cloud servers, among others. Data from each
 366 source is included in a different dimension in the data model, according to its characteris-
 367 tics. The dimensions are the following.

368 **Weather dimension:** Contains weather data; for instance, temperature and the
 369 amount of water on the farm.

370 **Paddock dimension:** Stores data of the paddocks on the farm; for instance, area and
371 forage capacity.

372 **Soil dimension:** Stores soil data; for instance, physicochemical variables of each
373 paddock.

374 **Animal dimension:** Stores animal data; for instance, weight, breed and age.

375 **Lot dimension:** Stores data of the batches of animals that are in the process of
376 fattening.

377 **Grass dimension:** Stores the data of the pasture; for instance, its type, maximum
378 height and minimum height.

379 In general, data is extracted from different sources following different strategies. For
380 example, when they are extracted from farm databases they follow a traditional data
381 extract-transform-load approach, when they are extracted from the Internet is used a
382 natural language processing approach, and so on for the rest of the sources. Then, they
383 go through a phase in the data management layer that is in charge of data pre-processing,
384 which includes data cleaning and normalization, the elimination of invalid and atypical
385 data, among other things, and culminates with a feature engineering process that allows
386 determining the variables required for the construction of the different knowledge models
387 of the ACODAT data analysis tasks.

388 5 Case study: "El Rosario" cattle farm

389 For this case study, this section presents the experimental context and the instantiation of
390 ACPLF-003 (Animal monitoring).

391 5.1 Experimental context

392 In this case study, we used data from "El Rosario" cattle farm, located 5 km from the city
393 of Monteria, Colombia. This farm focuses on beef-production with fattening cattle. The
394 farm is certified in good cattle-raising practices by the *Colombian Agricultural Institute*
395 *(in Spanish, ICA)* [39]. The farm is on the road to obtain the *Rainforest Alliance certifi-*
396 *cation*. Rainforest Alliance is an international non-governmental organization that works
397 to conserve biodiversity and ensure sustainable livelihoods [40].

398 To illustrate the functionality of ACPLF-000, this case study discusses ACPLF-003, in
399 an animal monitoring process, according to the following scenario. The cattle farm has 18
400 lots of animals with an average of 45 animals per lot, equivalent to 810 fattening animals.
401 These animals begin their fattening process with an average of 300 to 350 kilograms, with
402 an average age of two years old. The animals must arrive to the slaughterhouse with an
403 average of 450 to 550 kilograms, in a maximum of 14 months of fattening (which means
404 they gain an average of 20 kilograms per month).

405 In the process of weight gain, the farmer must have enough food, water and nutrients
406 to meet the weight gain demands required by the market. The fattening process requires
407 a constant monitoring of different variables; for instance, climate, forage, animal weight
408 and animal health. During the 14 months of fattening, the farmer, based on his experience
409 and the advice of a veterinarian, or when necessary due to any eventuality that may arise
410 during the process (e.g., infection, worms or skin cuts), vaccinates –frequently– the animals
411 with antiparasitics, gives vitamins.

412 During the fattening, decisions are also taken about the paddocks, and the batch of
413 animals that should be moved to based on the farmer's experience. The farmer chooses,
414 empirically, which paddock should be occupied or not depending on (i) forage capacity, (ii)
415 watering capacity, and (iii) which paddock has shade to improve animal welfare.

416 5.2 Instantiation of ACPLF-003: Animal Fattening

417 The instantiation of ACPLF-003 must consider, for instance, disease detection, vaccination
 418 plan, paddock availability and climate. The following steps describe how ACPLF-003 is
 419 instanced for this case study.

420 **Task 1. Weighing task:** The first task is to –automatically– determine the weight of
 421 cattle, for which a prediction model is used. The prediction model is built with historical
 422 data found in the farm’s livestock software. The prediction model also uses variables such
 423 as i) breed, ii) age, (iii) sex, (iv) climate, (v) temperature and (vi) pasture quality to explain
 424 an increase or decrease in weight. In what follows, two cases of this task are presented.

- 425 • **Case 1:** An animal weighs 340 kg. The model estimates that it should have gained
 426 338 kg. In this case, Task 2 would not be performed, since the animal gained the
 427 desired weight gain.
- 428 • **Case 2:** An animal weighs 300 kg, but the model estimated that it should have
 429 gained 325 kg, as presented in Table 5 (see Animal Id 00734). Since the conditions
 430 were favorable for weight gain (e.g., quality of pasture and climate), in this case, a
 431 warning to the farmer is generated so that he can take the appropriate decisions.

Table 5: Predictions generated by the weighting task

Lot Id	Animal Id	Age	Weight	Predicted weight
L20-034	00732	1,5	330	327
L20-034	00733	1,6	320	319
L20-034	00734	1,6	300	325
L20-034	00735	1,4	340	338

432 **Task 2. Vaccination task:** The second task uses a prescriptive model, which is
 433 built with the (i) farm’s historical data, (ii) websites selling animal-feed supplements, (iii)
 434 animal medications, and a (iv) database of bovine diseases or parasites. The prescriptive
 435 model is activated depending on the weight gain/loss in the first task. As an example, in
 436 the second case, presented in Task 1, an animal weighs 300 kg and Task 1 estimated that
 437 it should weight 325 kg. This condition would invoke the prescriptive model to define a
 438 nutrition plan with vitamins or other supplements, as presented in Table 6.

Table 6: Prescription generated by the vaccination task

Lot Id	Animal Id	Prescription
L20-034	00734	Anti-partisan
L20-034	00734	Genablic acid
L20-034	00734	Mineralized salt

439 **Task 3. Rotation task:** In the third task, the system will use an assignment model
 440 that uses environmental data to make an intelligent planning about where it is best to move
 441 a batch of animals. The assignment model takes into account (i) the quality of pasture,
 442 (ii) resting times, (iii) occupation, (iv) climate and (v) animal welfare (e.g., percentage of
 443 shade and access to water). Thus, this task will assign the best paddock to move the batch
 444 of animals to maximize meat production based on a self-planning scheme. As an example,
 445 the assignment model of Table 7 shows the planning of animal rotation (to which paddock
 446 to rotate), the duration of the occupancy, and the resting times of the paddocks.

Table 7: Assignment model generated by the rotation task

Lot ID	Quantity of animals	Average weight	Date in	Date out	Paddock	Occupancy time	Resting time
L20-034	28	300	4/01/20	8/01/20	P045	4	45
L20-034	28	303,6	8/01/20	12/01/20	P048	4	35
L20-034	28	305,4	12/01/20	14/01/20	P049	2	36
L20-034	28	307,2	14/01/20	16/01/20	P050	2	37
L20-034	28	309,9	16/01/20	19/01/20	P055	3	38
L20-034	28	311,7	19/01/20	21/01/20	P052	2	39
L20-034	28	314,4	21/01/20	24/01/20	P059	3	45
L20-034	28	316,2	24/01/20	26/01/20	P060	2	30
L20-034	28	318	26/01/20	28/01/20	P065	2	35

447 6 General Analysis

448 6.1 Comparison with Previous Works

449 In this section, we propose criteria to analyze beef-production automation in the context
 450 of PLF. The criteria that have been considered are desired aspects in PLF. For example,
 451 carry out everything-mining to exploit the available data. Also, automate the entire beef
 452 production process, considering the variables that directly or indirectly affect the animal,
 453 such as the pasture. On the other hand, the third criterion points to a holistic vision of the
 454 problem that must consider the relationship between soil, forage and animal. Finally, the
 455 possibility of adding aspects of environmental sustainability to model the beef production
 456 process, in order to assess its benefits, is a very important element to consider. These
 457 general criteria are within the scope of the PLF and are aspired to be achieved. In this
 458 section, we have focused on determining whether the works comply with some of these
 459 aspects, and not on how they methodologically do so. Next, we make a comparison of this
 460 work with previous works based on these criteria.

461 *Criterion 1:* The entire beef-production process is automatized.

462 *Criterion 2:* Everything-mining techniques are used in the production process.

463 *Criterion 3:* Grazing and animal welfare are analyzed together.

464 *Criterion 4:* Efficient and environmentally-friendly production is considered.

465 In Table 8, a qualitative comparison with related works is made, based on previous
 466 criteria (✓ means the work meets that criteria and ✗ means it doesn't).

Table 8: Comparison with previous works.

	Criterion 1	Criterion 2	Criterion 3	Criterion 4
[17]	✗	✓	✓	✗
[18]	✗	✓	✗	✗
[19]	✗	✗	✗	✗
[20]	✗	✓	✓	✗
[21]	✗	✗	✓	✗
[22]	✗	✗	✓	✗
This work	✓	✓	✓	✓

467 As shown in Table 8, related papers did not satisfy all the criteria. Specifically, in
 468 criterion 1, this research allows, by means of ACs, the automation of the whole production

469 process. For this automation, paradigms such as multi-agent systems need to be used, in
470 conjunction with the ACODAT architecture, to model the entire production process [41].

471 For criterion 2, Segerkvist *et al.* [17] and Feng *et al.* [18] worked on the estimation of
472 animal weight based on data mining. The basis of our proposal is an autonomous decision-
473 making through data, with knowledge extracted from animal production. Thus, this work
474 is based on everything-mining techniques.

475 For criterion 3, Segerkvist *et al.* focused on the detection of infections that reduce
476 weight gain, something fundamental for animal welfare. In addition, Fuentes *et al.* [20]
477 focused on animal welfare, specifically, in the reduction of heat stress by providing an
478 automatic evaluation of animal welfare. Jung *et al.* [19] used wireless sensor networks, to
479 monitor farm animals, using IoT equipment and cloud platforms. Vayssade *et al.* [21] and
480 Li *et al.* [22] worked with drones for farm-data capture and monitoring tasks. Vayssade *et al.*
481 *al.* used image processing for animal activity detection, and Li *et al.* used drones to au-
482 tonomously track and monitor livestock. This proposal takes into account animal-welfare,
483 soil, and pasture to perform rotations, in addition, this proposal includes a prescriptive
484 model to improve animal health.

485 Finally, for criterion 4, this proposal meets the criterion of efficient and environmentally-
486 friendly production because the farmer can know what is the maximum number of animals
487 per season that can support her/his farm. This reduces greenhouse gases, and makes the
488 farm more productive and sustainable.

489 6.2 Discussion of Preliminary Results

490 As mentioned before, in this work, the theoretical design of several ACODATs for self-
491 management of the beef production process has been presented. However, the development
492 of some of the tasks defined in these ACODATs have been carried out in previous works.
493 For example, the ACODAT responsible for the animal fattening supervision process has
494 two tasks, the detection of abnormalities in the fattening process and the diagnosis of what
495 may be happening in the animal. Both tasks have already been carried out in previous
496 works, with very stimulating results.

497 For example, the task that defines the animal fattening identification model was per-
498 formed in [14], which allows the detection of anomalies in cattle weight gain over time.
499 For the development of this task, the CRISP-DM methodology was used. In that work,
500 the performance of various machine learning techniques was compared, and an outlier de-
501 tection process was performed to identify outlier weights. In general, the results showed a
502 performance with an average Mean Absolute Error (MAE) of 5.4 kg, which is quite good
503 for cattle weights of the order of 400 kg.

504 Regarding the task to diagnose the anomaly detected in the fattening process of cattle
505 in rotational grazing, a fuzzy classification system was used in [15]. For the development of
506 this task, the KDD methodology was used. The fuzzy classifier uses the fuzzy reasoning to
507 determine the current situation before a given input and the genetic algorithms to optimize
508 the rules to improve diagnosis. The results of the tests carried out indicate that the quality
509 of the fuzzy classification system is very good. The value of the Area Under the Curve that
510 measures the sensitivity and specificity of the system is 1 (indicates a precision of 100% in
511 the diagnosis); and the certainty of the rules it optimizes (determines the average degree
512 of their firing), in the end, have a value of 0.85, which is very good.

513 Specifically, this paper shows the implementation of the autonomous self-planning cycle
514 as the first step toward semi-autonomous production processes, in the context of PLF. The
515 described autonomous cycle was methodologically detailed using MIDANO, to achieve the
516 desired results. This means that this AC achieved the designed objectives of animal-
517 rotation planning, aiming to incorporate autonomy in the beef production process. The

518 preliminary results indicated in this section show the viability of our proposal, and motivate
519 the future development of all the ACODATs defined in this work.

520 7 Conclusions and Future Work Directions

521 This paper presents an architecture to integrate and inter-operate actors in the context
522 of PLF. The architecture combines multiple variables; for instance, soil, animal welfare,
523 pasture, climate. The proposed architecture uses ACODAT and proposes several ACs to
524 give autonomy to the beef-production process. In addition, this article shows the instanti-
525 ation of an autonomous self-planning cycle as the first step towards efficient and effective
526 beef-production processes.

527 Other results of this research are (i) the use of environmental variables to make decisions
528 on optimal grazing, (ii) the ability to use everything-mining techniques to improve the
529 knowledge of the system and decision-making processes (.e.g., data mining, text mining
530 and web-mining techniques), (iii) real-time analysis for a sustainable and environmentally-
531 friendly livestock production , and (iv) use of PLF and PAF combined and managed by CAs
532 capable of adapting to the beef production process. Thanks to the concept of “autonomous
533 data analysis cycles”, the model can self-adjust to new environmental constraints, as well
534 as to growth/decrease in forage demand, among other events. For this purpose, several
535 data analytics techniques are used, which autonomously work to make decisions.

536 Particularly, the case study shows that everything-mining techniques are needed to
537 address self-planning in rotational grazing. This case study serves as a guide to incor-
538 porate self-management in a beef-production process. Finally, the implementation of
539 this case study will allow us to evaluate the impact of this self-management approach
540 of beef-production processes, in the context of PLF, based on the autonomous-computing
541 paradigm and everything-mining techniques.

542 Future work is aimed to implement this framework in a simulated environment to
543 verify the functionalities of this solution. In this sense, we plan to use historical data of
544 "El Rosario" Cattle Farm to develop the different data-analysis tasks (e.g., to determine
545 weight gains or losses in the rotation of animal flocks). Another important future work
546 is to develop specific ACs to evaluate autonomic processes to configure and reconfigure a
547 livestock farm, in the context of PLF, according to this architecture.

548 Finally, one of the biggest challenges to implement this type of system is the cost as-
549 sociated with the sensors for data acquisition. In addition to the optimal distribution of
550 these sensors, Internet connectivity and stable electricity-flow on the farm are big chal-
551 lenges. Future studies should analyze these uncertain aspects and how to consider them
552 in the proposed architecture.

553 Acknowledgements

554
555 Rodrigo García is supported by a PhD grant financed by Universidad EAFIT. All the
556 authors would like to thank the "Vicerrectoría de Descubrimiento y Creación", of Univer-
557 sidad EAFIT, for their support on this research.

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